

A MODEL OF AN ELECTRIC ARM

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ABSTRACT

In this project report, I shall talk more in detail about my project with a title of Electric Robot Arm. It consists of the robotic arm general information, types of grippers. Gripper's forces, movements of my model and how it works.

For the movements of my model, I will show how my model gripper shall move. Besides that, I also talk on degree of freedom, which a robot should have.